## Please read this manual before installation and use.

## GENERAL

It composed of wafer type butterfly valve and high-power electric actuator.

Actuator
AD1 : For AC power
AD2 : For AC / DC power
AD0 : For DC power
HD1 : For AC power (High speed)


HD2 : For AC / DC power (High speed)
HDO : For DC power (High speed)
AE1 : For AC power
AE2 : For AC power

Valve
F type FCD450 body.
FN type FCD450 body.
FE type Aluminum alloy diecast body. (lightweight)


FZ type Long neck.
FP type For Corrosion resistance. (Polypropylene body)

PRODUCT CODE

(1) Actuator

AD1 AD2 AD0
HD1 HD2 HD0
AE1 AE2
(2) Valve

F- FN FE FP
FZ
(3) Voltage

1: 100 / 110 V AC
2 : 200 / 220 V AC
0 : 24 V DC
(4) Sizing code 0 : Standard 1 : Light 2 : Heavy
(5) Connection 1 : JIS 10K
(6) Body material

D : FCD450
L: ADC12
Q : PP
(7) Disc material

D : FCD450
U : SUSF316 / SCS14
A: CAC703
T: SCS13A
J : PPS
Q: PP
(8) Seat material

E : EPDM
B: NBR
V : FKM
(9) Size $[\mathrm{mm}]$
ex. $80 \mathrm{~A} \rightarrow 080$

F FN FE FP type

| Valve type |  | F |  | FN | FE | FP |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Design |  | Wafer type |  | Wafer type | Wafer type | Wafer type |  |
| Connection |  | JIS Flanges 10K |  | JIS Flanges 5K／10K | JIS Flanges 10K | JIS Flanges 10K |  |
| Fluid |  | 直OG 80．m |  | 直（0）cm | 直 $\underbrace{\circ}$ | 直 3 m |  |
| Max pressure |  | 1 MPa | 0．5 MPa | 1 MPa | 0．98 MPa | 1 MPa | 0．7 MPa |
| Size［mm］ |  | 050 to 250 | 300 | 050 to 200 | 040 to 300 | 040 to 150 | 200 to 300 |
| Material | Body | FCD450 |  | FCD450 | ADC12 | PP |  |
|  | Disc | FCD450（CNi plated） CAC703 SUSF316／SCS14 |  | FCD450（CNi plated） CAC703 <br> SUSF316／SCS14 | SCS13A | PP |  |
|  | Seat | EPDM NBR | FKM | EPDM NBR | EPDM NBR | EPDM |  |
| Stem seal | O－ring | NBR | FKM | NBR | NBR | EPDM |  |

## PRESSURE \＆TEMPERATURE RATING

| F FN |  |  |
| :--- | :---: | :---: |
| Seat material | Fluid temp． | Use |
| EPDM | -20 to $+80^{\circ} \mathrm{C}$ | 直 |
| NBR | -10 to $+60^{\circ} \mathrm{C}$ | $\boxed{3}$ |
| FKM | -5 to $+80^{\circ} \mathrm{C}$ | $\zeta^{\circ}$ |



FP


NOTE）• EPDM is not recommended for hydrocarbon－based oil or grease．
－Hot water can be used at temperatures of up to $80^{\circ} \mathrm{C}\left(\mathrm{FE}: 90^{\circ} \mathrm{C}\right)$ ．Steam cannot be used．
－CAC703 and EPDM are suitable for seawater．（F，FN）

INHERENT FLOW CHARACTERISTIC


F FN
value（\％）

Range ability 30：1

FE
Cv value（\％）


Valve opening（\％）
Range ability 30：1

FP
Cv value（\％）


Valve opening（\％）
Range ability $30: 1$

VALVES SPECIFICATIONS

FZ type

| Valve type |  | FZ |  |
| :---: | :---: | :---: | :---: |
| Design |  | Wafer type |  |
| Connection |  | JIS Flanges 5K / 10K |  |
| Fluid |  | 直 6 |  |
| Max pressure |  | 1 MPa |  |
| Size [mm] |  | 040 to 300 | 040 to 200 |
| Material | Body | ADC12 |  |
|  | Disc | SCS14 | PPS |
|  | Seat | EPDM NBR |  |
| Stem seal | O-ring | NBR |  |

PRESSURE \& TEMPERATURE RATING


NOTE) • EPDM is not recommended for hydrocarbon-based oil or grease.

- Unsuitable for steam or hot water over $90^{\circ} \mathrm{C}$. (Steam cannot be used.)

INHERENT FLOW CHARACTERISTIC


Range ability $30: 1$

## ELECTRIC ACTUATOR SPECIFICATIONS

AD1 HD1 type

| Actuator type ( $\square$ :Voltage code) | AD1-300-■ | AD1-700-■ | HD1-300-■ | HD1-700-■ | HD1-02K- $\square$ | HD1-06K- $\square$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | $100 / 110 \vee \mathrm{AC} \pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 1) <br> $200 / 220 \vee \mathrm{AC} \pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 2) |  |  |  |  |  |
| Rated torque [ $\mathrm{N} \cdot \mathrm{m}$ ] | 30 | 70 | 30 | 70 | 200 | 600 |
| Operation time [s] | 3 to 4 | 6 to 10 | 1 to 2 | 3 to 5 | 8 to 15 | 24 to 45 |
| Power consumption (Max) [VA] | $100 \times 150$ |  |  |  |  |  |
| Motor | DC motor |  |  |  |  |  |
| Overload protection | Thermistor |  |  |  |  |  |
| Method of operation | Transfer input type |  |  |  |  |  |
| Operation | Power to $\mathrm{S} \rightarrow$ SHUT (SHUT PL is lit.) Power to $\mathrm{O} \rightarrow$ OPEN (OPEN PL is lit.) |  |  |  |  |  |
| Output signal rating | Resistance load 10 A 250 V AC (Minimum 27 mA ) |  |  |  |  |  |
| Duty cycle | $20 \% 15 \mathrm{~min}$. (When ambient temperature is over $50{ }^{\circ} \mathrm{C}, 10 \% 15 \mathrm{~min}$.) |  |  |  |  |  |
| Ambient temperature | -20 to $55^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Space heater | 0.8 W |  |  |  |  |  |
| Manual operation | Manual over-ride with clutch. <br> (Direct operation / 06K: Operation by manual shaft.) |  |  |  |  |  |
| Enclosure | Equivalent to IP65 (IEC 60529) |  |  |  |  |  |
| Housing material | Aluminum alloy diecast (acrylic resin baking finish) |  |  |  |  |  |
| Wire connection | Terminal Block: M3, Ground terminal: M3 |  |  |  |  |  |
| Conduct port | 2-G1/2 Attachments: Cable gland (for Ф6 to 12 mm cable), plug. |  |  |  |  |  |

WIRING


## ELECTRIC ACTUATOR SPECIFICATIONS

AD2 HD2 type

| Actuator type ( $\square$ :Voltage code) | AD2-300-■ | AD2-700-■ | HD2-300- $\square$ | HD2-700-■ | HD2-02K- $\square$ | HD2-06K- $\square$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | $100 / 110$ V AC $\pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 1) <br> $200 / 220$ V AC $\pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 2) <br> 24 V DC  (Code: 0) |  |  |  |  |  |
| Rated torque [ $\mathrm{N} \cdot \mathrm{m}$ ] | 30 | 70 | 30 | 70 | 200 | 600 |
| Operation time [s] | 3 to 4 | 6 to 10 | 1 to 2 | 3 to 5 | $\begin{array}{lr} \text { AC: } 8 \text { to } 15 \\ \text { DC: } 12 \text { to } 17 \end{array}$ | AC: 24 to 45 DC: 36 to 50 |
| Power consumption (Max) [VA] | $\begin{array}{lr} \text { AC: } & 100 \\ \text { DC: } & 80 \end{array}$ |  | $\begin{aligned} & \text { AC: } 150 \\ & \text { DC: } 120 \end{aligned}$ |  |  |  |
| Motor | DC motor |  |  |  |  |  |
| Overload protection | Current limiter |  |  |  |  |  |
| Method of operation | a-contactinput type, with built-in relay |  |  |  |  |  |
| Operation | $\begin{array}{ll} \text { SW is OFF } & \rightarrow \text { SHUT (R3 SW is ON) } \\ \text { SW is ON } & \rightarrow \text { OPEN (R4 SW is ON) } \\ \text { Over torque } & \rightarrow \text { R5 SW is ON } \end{array}$ |  |  |  |  |  |
| Input signal current | 10 mA 100 V AC / 6.5 mA 200 V AC / 38 mA 24 V DC (Leakage current in SW: less than 1 mA ) *O terminal input: Photo coupler |  |  |  |  |  |
| Output signal rating | Resistance load 0.5 A 125 V AC 1 A 24 V DC |  |  |  |  |  |
|  | Micro load 1 mA 5 V DC |  |  |  |  |  |
| Alarm signal | Output when the motor protection circuit operates by the overload. (it returns by power supply OFF or reverse operating signal) |  |  |  |  |  |
| Duty cycle | $20 \% 15 \mathrm{~min}$. (When ambient temperature is over $50{ }^{\circ} \mathrm{C}, 10 \% 15 \mathrm{~min}$.) |  |  |  |  |  |
| Ambient temperature | -20 to $55^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Space heater | 0.8 W |  |  |  |  |  |
| Manual operation | Manual over-ride with clutch. <br> (Direct operation / 06K: Operation by manual shaft.) |  |  |  |  |  |
| Enclosure | Equivalent to IP65 (IEC 60529) |  |  |  |  |  |
| Housing material | Aluminum alloy diecast (acrylic resin baking finish) |  |  |  |  |  |
| Wire connection | Terminal Block: M3, Ground terminal: M3 |  |  |  |  |  |
| Conduct port | 2-G1/2 Attachments: Cable gland (for $\Phi 6$ to 12 mm cable), plug. |  |  |  |  |  |

WIRING


## ELECTRIC ACTUATOR SPECIFICATIONS

ADO HDO type

| Actuator type | AD0-300-0 | AD0-700-0 | HD0-300-0 | HD0-700-0 | HD0-02K-0 | HD0-06K-0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | 24 V DC |  |  |  |  |  |
| Rated torque [ $\mathrm{N} \cdot \mathrm{m}$ ] | 30 | 70 | 30 | 70 | 200 | 600 |
| Operation time [s] | 3 to 4 | 6 to 10 | 1 to 2 | 3 to 5 | 12 to 17 | 36 to 50 |
| Power consumption (Max) [VA] | 80 |  | 120 |  |  |  |
| Motor | DC motor |  |  |  |  |  |
| Overload protection | Current limiter |  |  |  |  |  |
| Method of operation | Switching polarity type |  |  |  |  |  |
| Operation | $\begin{array}{ll} 2+3- & \rightarrow \text { SHUT (SHUT PL is lit.) } \\ 3+2- & \rightarrow \text { OPEN (OPEN PL is lit.) } \end{array}$ <br> Over torque $\rightarrow$ Alarm PL is lit. |  |  |  |  |  |
| Output signal rating | Resistance load 1 A to 35 mA 24 V DC |  |  |  |  |  |
| Duty cycle | $20 \% 15 \mathrm{~min}$. (When ambient temperature is over $50^{\circ} \mathrm{C}, 10 \% 15 \mathrm{~min}$.) |  |  |  |  |  |
| Ambient temperature | -20 to $55^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Space heater | 3 W |  | Space heater |  |  |  |
| Manual operation | Manual over-ride with clutch. <br> (Direct operation / 06K: Operation by manual shaft.) |  |  |  |  |  |
| Enclosure | Equivalent to IP65 (IEC 60529) |  |  |  |  |  |
| Housing material | Aluminum alloy diecast (acrylic resin baking finish) |  |  |  |  |  |
| Wire connection | Terminal Block: M3, Ground terminal: M3 |  |  |  |  |  |
| Conduct port | 2-G1/2 Attachments: Cable gland (for Ф6 to 12 mm cable), plug. |  |  |  |  |  |

WIRING


## ELECTRIC ACTUATOR SPECIFICATIONS

AE1 type

| Actuator type ( $\square$ :Voltage code) | AE1-120-■ | AE1-300- $\square$ | AE1-600-■ | AE1-02K- $\square$ | AE1-06K- $\square$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | $100 / 110$ V AC $\pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 1) <br> $200 / 220$ V AC $\pm 10 \%$ $50 / 60 \mathrm{~Hz}$ (Code: 2) |  |  |  |  |
| Rated torque $[\mathrm{N} \cdot \mathrm{m}]$ | 12 | 30 | 60 | 200 | 600 |
| Operation time [s] | $\begin{aligned} & 10 / 8.5 \\ & (50 / 60 \mathrm{~Hz}) \end{aligned}$ | $\begin{aligned} & 7.2 / 6 \\ & (50 / 60 \mathrm{~Hz}) \end{aligned}$ | $\begin{aligned} & 15 / 12 \\ & (50 / 60 \mathrm{~Hz}) \end{aligned}$ | $\begin{array}{\|l\|} \hline 30 / 25 \\ (50 / 60 \mathrm{~Hz}) \end{array}$ |  |
| Power consumption [VA] | 19 | 60 |  | 110 | 350 |
| Motor | Synchronous motor | Reversible motor self-contained mechanical brake |  |  |  |
| Overload protection | Thermal protector |  |  |  |  |
| Method of operation | Transfer input type |  |  |  |  |
| Operation | Power to $S \rightarrow$ SHUT (SHUT PL is lit.) <br> Power to $\mathrm{O} \rightarrow$ OPEN (OPEN PL is lit.) |  |  |  |  |
| Output signal rating | Resistance load 3 A 250 V AC (Minimum 0.1 A) |  |  |  |  |
| Duty cycle | 20 \% 15 min . |  |  |  |  |
| Ambient temperature | -20 to $55^{\circ} \mathrm{C}$ |  |  |  |  |
| Space heater | 3 W |  |  |  |  |
| Manual operation | Manual shaft |  |  |  |  |
| Enclosure | Equivalent to IP65 (IEC 60529) |  |  |  |  |
| Housing material | Aluminum alloy diecast (acrylic resin baking finish) |  |  |  |  |
| Wire connection | Terminal Block: M3, Ground terminal: M3 |  |  |  |  |
| Conduct port | 2-G1/2 Attachments: Cable gland (for $\Phi 6$ to 12 mm cable), plug. |  |  |  |  |

WIRING


Note) Control switch should be prepared one by one for actuator.
Do not operate two or more actuator from one switch. It might malfunction.

## ELECTRIC ACTUATOR SPECIFICATIONS

AE2 type

| Actuator type ( $\square$ :Voltage code) | AE2-120- $\square$ | AE2-300- $\square$ | AE2-600- $\square$ | AE2-02K- $\square$ | AE2-06K- $\square$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Voltage | $100 / 110$ V AC $\pm 10 \%$ $50 / 60 \mathrm{~Hz}$ <br> $200 / 220 \vee A C \pm 10 \%$ $50 / 60 \mathrm{~Hz}$ |  | (Code: 1) <br> (Code: 2) |  |  |
| Rated torque [ $\mathrm{N} \cdot \mathrm{m}$ ] | 12 | 30 | 60 | 200 | 600 |
| Operation time [s] | $\begin{array}{\|l\|} \hline 11 / 9.5 \\ (50 / 60 \mathrm{~Hz}) \end{array}$ | $\begin{aligned} & 8.2 / 7 \\ & (50 / 60 \mathrm{~Hz}) \end{aligned}$ | $\begin{array}{\|l\|} \hline 16 / 13 \\ (50 / 60 \mathrm{~Hz}) \end{array}$ | $\begin{array}{\|l\|} \hline 31 / 26 \\ (50 / 60 \mathrm{~Hz}) \end{array}$ |  |
| Power consumption [VA] | 26 | 60 |  | 110 | 350 |
| Motor | Synchronous motor | Reversible motor self-contained mechanical brake |  |  |  |
| Overload protection | Timer |  |  |  |  |
| Method of operation | a-contactinput type, with built-in relay |  |  |  |  |
| Operation | SW is OFF $\rightarrow$ SHUT (SHUT signal is output. ) <br> SW is ON $\rightarrow$ OPEN (OPEN signal is output. ) <br> Overtorque $\rightarrow$ Alarm signal is output |  |  |  |  |
| Input signal current | 9 mA (O-terminal) Leakage current in SW: less than 1 mA |  |  |  |  |
| Output signal rating | Resistance load 0.5 A 125 V AC 1 A 24 V DC |  |  |  |  |
|  | Micro load 1 mA 5 V DC |  |  |  |  |
| Alarm signal | Output when the motor protection circuit operates by the overload. (it returns by power supply OFF or reverse operating signal) |  |  |  |  |
| Duty cycle | 20 \% 15 min . |  |  |  |  |
| Ambient temperature | -20 to $55^{\circ} \mathrm{C}$ |  |  |  |  |
| Space heater | 3 W |  |  |  |  |
| Manual operation | Manual shaft |  |  |  |  |
| Enclosure | Equivalent to IP65 (IEC 60529) |  |  |  |  |
| Housing material | Aluminum alloy diecast (acrylic resin baking finish) |  |  |  |  |
| Wire connection | Terminal Block: M3, Ground terminal: M3 |  |  |  |  |
| Conduct port | 2-G1/2 Attachments: Cable gland (for $\Phi 6$ to 12 mm cable), plug. |  |  |  |  |

WIRING


Note) Do not use control switch with current leakage (more than 1 mA ) such as TRIAC or relay with CR.

OPTIONAL PARTS

| Specifications | Code No. | AD | HD | AE | Remarks |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :--- |
| Auxiliary <br> limit switch | Select limit switch <br> depending on the load | L0 | O | O | O | For standard signal |
|  | L2 | O | O | O | For micro load signal |  |
| OPEN/CLOSE speed control board | IO | O |  |  | Set the operating time between 1.5 and 30 times. |  |
| Manual lever handle | M0 | O | O |  | Mounted on the drive shaft. (except 06K) |  |
| *Auxiliary limit switch: Please refer to the specifications. |  |  |  |  |  |  |

WIRING (OPTION)

| L0, L2 Auxiliary limit switch | 10 Speed control board (only for AD series) |
| :---: | :---: |
|  <br> At CLOSE side, LC and LS is ON. At OPEN side, LC and LO is ON. <br> ON point can be reset by adjusting the cam. | Operating speed (OPEN/CLOSE) can be adjusted by "OPEN"/"SHUT" trimmer. Turning clockwise increases the operating time. |

DIMENSIONS


Parts name

| 1 | Body | 6 | Limit switch | 11 | Manual shaft (For 06K) |
| :---: | :--- | :---: | :--- | :---: | :--- |
| 2 | Motor cover | 7 | SW setting cam | 12 | Rubber packing |
| 3 | Motor | 8 | Transformer |  |  |
| 4 | Control board | 9 | Drive shaft |  |  |
| 5 | Terminal block | 10 | Manual clutch |  |  |

AE


Parts name

| 1 | Body | 5 | Terminal block | 9 | Manual shaft |
| :---: | :--- | :---: | :--- | :---: | :--- |
| 2 | Motor cover | 6 | Limit switch | 10 | Rubber packing |
| 3 | Motor | 7 | SW setting cam |  |  |
| 4 | Control board | 8 | Drive shaft |  |  |

## HANDLING \& STORAGE

## (1)HANDLING

Do not drop or throw the product as it may break.
(2)STORAGE

- Store away from dust, moisture and direct sunlight. If possible, store in the original package.
- Do not remove a dust proof cap until the piping.
(3)CHECKING
- Check the product code, power supply, and voltage before installation.
- Make sure that the bolts are not loose.


## INSTALLATION

## (1)PRECAUTIONS

- Flush the pipeline carefully before installing the valve. Foreign particles, such as sand or pieces of welding electrode, will damage the disk and seats.
- Seat has ribs for tight gasket seating. Do not use gasket.
- Valve is shipped closed. (allows quick piping.)
- Disc interference may also occur when valve is installed in pipeline with smaller than normal inside diameter such as thick wall pipe, or lining pipe. Suitable corrective measurement must be taken (taper boring the pipe or pipe liner, etc.)
- When you use a vinyl chloride flange, there is a caliber to be internal off the corners. Please cut off the corners with reference to the following. (F, FN)

| Valve size [mm] |  | Chamfer |
| :---: | :---: | :---: |
| $[\mathrm{mm}]$ |  |  |

- Avoid oil or grease when using EPDM seat.
(2)PIPING FLANGES (F, FN, FE, FZ)
- Class JIS 5K and JIS 10K pipe flanges can be used for FN series. See the drawing below for centering the valve with bolts.

> JIS 5K JIS 10K


- FZ type has T bar on bolt guide hole.

Flanged-part


The form of flanged-part is different depending on the size.

- Wafer type butterfly valve is put between two seats of flanged-end and tightened with long bolts.
- Before bolts are tightened, valve should be centered within the bolts to prevent possible disc interference or damage by contact with the pipe or flange.
- Tighten all bolts using crossover method to load the joint evenly.
- When using a resin flange, if the connecting bolt is tightened too much, the flange may deform and leak.

| Valve size [mm] |  |  | Recommended <br> torque $[\mathrm{N} \cdot \mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| F | FN | FE FZ |  |
| 050 | 050 | 040 |  |
| 065 | 065 | 050 | 20 |
| 080 | 080 | 065 |  |
| 100 | 100 | 080 |  |
| 125 | 125 | 125 |  |
| 150 | 150 | 150 | 25 |
| 200 | 200 | 200 |  |
| 250 |  | 250 | 30 |
| 300 | - | 300 |  |

(3)CAUTION ON PLASTIC VALVE (FP)

Flange connection

- Use same material as same as opposite piping flanged. For metal piping, use flanged washer and it is considered that there is no heavy piping stress.
- When the piping, wick gap between a pipe and a valve and a bending cause by an angle difference, it may cause switching incompatible breakage, and leakage from fluid.
- Shaft, face to face dimension distance and flanged angle unit correctly.
- Use the flanged bolt on by bolt side and nut side, tighten all bolts using crossover method to load the joint evenly.

| Valve size [mm] | Recommended <br> torques [N•m] |
| :---: | :---: |
| 040 |  |
| 050 | 20 |
| 065 |  |
| 080 | 25 |
| 100 |  |
| 125 | 60 |
| 150 |  |
| 200 |  |
| 250 |  |
| 300 |  |

Expansion measure of pipe line

- Heat expansion occurs in pipe line depends on by temperature change after piping and temperature condition of internal fluid. Compression or contraction by heat stress acts also on a valve. Especially for metal piping, it happens to plastic valve as weak in intensity. Perform expansion treatment before or after a valve and it is considered that a burden is not placed on valve.


## (4)ENVIRONMENT

- Do not install in place where corrosive gas is present or where vibration is heavy ( 0.5 G or more).
-When radiant heat causes the surface temperature of the control unit to exceed $55^{\circ} \mathrm{C}$, provide an appropriate shielding plate.
- If there is a possibility that the fluid and drive part freeze, please take measures to prevent freezing.
(5)POSITIONING

Should be positioned through $90^{\circ}$ upward from horizontal. Provide space around the product to allow manual operation, inspection and replacement work.

Maintenance space for upper part of actuator.

| $\mathrm{AE}(120 / 300 / 600)$ |  | More than 105 mm |  |
| :--- | :--- | :--- | :--- |
| $\mathrm{AE}(02 \mathrm{~K} / 06 \mathrm{~K})$ | AD | HD | More than 120 mm |

## © ${ }^{(6) T H E R ~ N O T E S ~}$

Until the wiring is completed there must be no condensation or flooding in the interior of the actuator, after piping. Protective caps on the cable gland are not waterproof.

## WIRING

## (1)PRECAUTIONS

- Remove the actuator cover before wiring.
- Two G1/2 electrical connections are provided with a cable gland and plug. Usable cable size is $\Phi 6$ to 12 mm.
- When using a flexible tube, dew condensation may occur inside the actuator due to respiration from the inside of the tube and malfunction may result. Seal the flexible tube connector part with a sealant.
- Sealants that affect the electrical contacts should not be used inside the electric actuator.
- If long distance wiring or low voltage operation, check that terminal voltage is in the proper range.
(2)CONNECTION
- Do not wiring outdoors on a rainy day.
- Check the power supply and voltage. Connect the signal as shown in the wiring diagram. Do not connect unnecessarily terminal.
- Actuator should be electrically grounded. Use the terminal marked ( $\stackrel{\perp}{=}$ ) inside the actuator.


## PREVENT DEW CONDENSATION

- When installing the cover after wiring, perform the bolt by the temporary tightening procedure and the permanent tightening procedure to tightly and securely tighten the rubber packing so that water does not enter from the outside.
- Tighten the cable gland nut so that there is no leakage from the wire entrance.


## CONTROL

(1)AE1

Each control switch should be prepared one by one. Do not operate two or more from one switch at the same time.
(2)AD2, HD2, AE2

When using control switch with current leakage (more than 1 mA ) such as TRIAC or relay with CR, it can cause malfunction.
(3)DC POWER SUPPLY

- Battery or full wave rectification can be used.
- Consider an inrush current of motor.
(It is 1.5 to 3 times of consumed current.)
- When using a DC voltage, be selected the wire thickness by the wiring distance.
- Do not use power supply that require more than 1 second with rise and fall time.
(4)USE OF OPEN/SHUT SIGNALS Use signals within the capacity of output signal rating.


## OPERATION

(1)TESTING

- Make sure that power supply voltage is correct. Also check operating position, wiring, speed and signals.
- During trial operation, check that valve movement and OPEN and SHUT signals are correct.
(2)DUTY CYCLE

Confirm that the operation frequency is within the specified duty cycle.
Use beyond the load time rate range will affect product life. Also, it may cause burnout.

Duty cycle is a value that regulates the opening / closing frequency of the actuator. The meaning of $20 \% 15$ minutes for Duty cycle is that 3 minutes ( $20 \%$ of 15 minutes) operation is possible. The calculated value obtained by dividing 3 minutes by the operation time is the number of times of operation within 15 minutes.

## (3)ATTENTION

- Keep power supplied for built-in space heater to prevent condensation inside actuator.
- Do not touch the moving parts of actuator in operation.
- Do not insert a reverse signal during operation. It may shorten the life of product.
- Never put anything on the actuator or make it into a foothold.


## MANUAL OPERATION

## (1)PRECAUTIONS

- Be sure to turn off the power before manual operation.
- Operate manually with reference to the opening degree label. Do not turn beyond the fully open / fully closed position. Operation failure may occur during automatic operation.
(2)THE WAY OF OPERATION


Manual operation can be possible by pulling down manual clutch knob. Set the knob to manual position and operate the joint by using an adjustable wrench in the SHUT/OPEN direction. When it becomes in the position besides the range of operation in the case of manual operation, it may stopped automatic moving.
In case the manual clutch knob is not easy to pull down, try moving joint or manual shaft to the opposite direction by wrench. For automatic operation, reset the knob to automatic position.
Be sure to confirm that knob is reset completely.


Turn manual shaft slowly with an adjustable wrench.

## MAINTENANCE

- To prevent electric shock, be sure to turn off the power when removing the actuator cover.
- Do the routine maintenance at least once in half a year.
Inspection items
- Confirm operation of opening and closing.
- Confirm that an actuator is not hot excessively.
- Confirm existence of abnormal noise and vibration during operation.
- Confirm whether screws are loose or not.
- Confirm that water or condensation no remains in the actuator.
- Confirm the fluid temperature or pressure.
- Confirm the leak from valve stem.
- Confirm the bolt tightening torque.

Before automatic operation, be sure to remove wrench.

## TROUBLE SHOOTING

| Problem | Cause | Solution |
| :---: | :---: | :---: |
| Actuator does not move. | Faulty wiring. | Correct the wiring. |
|  | No voltage is coming. | Check the voltage. |
|  | Incorrect voltage. | When it's burned out by excess voltage, replace the actuator. |
|  | Short the circuit, contact failure. | Review wires and connection. |
|  | Motor is too old. | Replace the actuator. Repair in our factory. |
| Operation is unstable. | Excess surge or voltage was applied. | - Replace the control board or limit switch. (Repair in our factory) <br> - Replace the actuator. |
|  | Rainwater entered the actuator. | - Dry the inside. <br> - Replace the actuator. |
|  | Added high harmonics noise from an inverter. | Attachment a filter for each inverter maker option. |
|  | Effect of high level noise. | Use the shielded wire and ground the wiring. Separate signal wire from power line. |
|  | Two or more valves operated by the same switch. <br> AE1 | Each control switch should be prepared one by one. |
|  | Switch leakage current is large. <br> AD2 HD2 <br> AE2 | Current leakage should be less than 1 mA . |


| Problem | Cause | Solution |
| :---: | :---: | :---: |
| Stop in the mid position. | There is a foreign object in the butterfly valve. | Remove a foreign object. |
|  | Valve is distorted. | Replace the valve. |
|  | Overload protector runs because of over-torque. | Turn off the power for about 3 minutes to remove a heat from motor protection circuit. AD1 HD1 AE1 |
|  |  | Motor protection circuit returns by the signal of operation of an opposite direction. Turn on the power again. <br> AD2 HD2 AE2 <br> AD0 HDO |
| Received the alarm signal. AD2 HD2 AE2 |  |  |
| Stop automatic moving after manual operation. AD HD | Manual clutch knob is not reset. | Reset manual clutch knob. |
|  | Out of operating range. (06K) | Reset by manual operation. |
| Leakage from valve stem | Stem packing is worn. | Replace the valve. |
|  |  | Replace the O-ring. F |
| Leakage from valve seat | Damaged on valve seat. | Replace the valve. |
|  |  | Replace the seat. F |

For more information contact
NIPPON VALVE CONTROLS, INC. for consultation.

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