SP-1516

Instruction manual

Electric Actuator PAX

GENERAL

A light weight, compact and long service life electric actuator built in high reliability and proportional motor.

PAX : For AC power.





PRODUCT CODE

P A X (1)	- [2] - (2)	(3) - (4) (5)		
(1) Actuator PAX	(2) Torque 050 120	(3) Voltage 1 : 100 / 110 V 2 : 200 / 220 V	(4) Option AK : Aluminum alloy motor cover C1 : Flexible cable	(5) Operation mode Nil : Mode A J : Mode B

3 way valve: SHUT / Position①, OPEN / Position②

Actuator type (□:Voltage code)		PAX-050-□	PAX-120-□	
Voltage		100 / 110 V AC ±10 % 50/60 Hz (Code: 1) 200 / 220 V AC ±10 % 50/60 Hz (Code: 2)		
Rated torque	[N·m]	5	12	
Operation time	[s]	14 / 12 (50/60 Hz)	30 / 25 (50/60 Hz)	
Power consumption [VA]		9.5		
Motor		Synchronous motor (Triac control)		
Overload protection		Impedance protect		
Method of operation		Proportional control		
Input signal		4 to 20 mA / 1 to 5 V (Input resistance: 250 Ω)		
Operation *1		[Mode A] SHUT by decreased signal ↔ OPEN by increased signal (Standard) [Mode B] SHUT by increased signal ↔ OPEN by decreased signal (Option: J)		
Indication signal		0 mA : SHUT \leftrightarrow 1 mA : OPEN (External load resistance: less than 3 k Ω) Common in mode A / B		
Resolution		Less than 0.2 %		
Duty cycle		100 %		
Ambient temperature		-20 to 55 °C		
Space heater		1 W		
Manual operation		Direct operation of actuator by loosening lock screw		
Enclosure		Equivalent to IP65 (IEC 60529)		
Housing material		Aluminum alloy die cast + Polycarbonate resin cover		
Terminal block		For bare wire 0.2 to 1.5 mm ² (AWG 26 to	16) Ground terminal: M3	
Conduct port		G3/8 Cable gland (for Φ5 to 10.5 mm cable)		

^{*1} Change by DIP switch. (Standard \rightarrow Mode B)

WIRING



ELECTRIC ACTUATOR SPECIFICATIONS

3 way valve: SHUT / Position ①, OPEN / Position ②

OPTIONAL PARTS

Specifications				PAX Remarks	
Aluminum alloy motor cover				0	
Flexible cable (Approx. 300 mm long)			C1	0	
Operation mode	SHUT by 4 mA.	(Decreased input signal)	Nil	0	Mode A (Standard)
	SHUT by 20 mA.	(Increased input signal)	J	0	Mode B

DIMENSION



ADJUSTMENT

 Dead band Turn the trimmer clockwise for wide the dead band as necessary. It is useful to prevent the hunting reaction of actuator. *Each trimmer on a built-in control board. 	Adjustment trimmer SPAN SHUT OPEN D.B.
② Operating range Do not adjust operating angle of a valve (OPEN, SHUT trimmer). Please contact us if you need to adjust operating angle.	ZERO DIP SW Image: Dip SW I
③ Operating speed (Speed control) No adjustment required. (ZERO, SPAN trimmer)	POWER 4~20 mA 0~1 mA T1 T2 I- I+ +

HANDLING & STORAGE

①HANDLING

Proper care in handling the actuator should be taken to prevent damage. Do not drop or throw it.

②STORAGE

Store the actuator in the protected area from dust, moisture, and direct sunlight. If possible, actuator should be kept in the original packaging.

③CHECKING

Check the product code, power supply, and voltage before installation.

INSTALLATION

- **①ENVIRONMENT**
- Do not install in place where corrosive gas is present or where vibration is heavy (0.5 G or more).
- When radiant heat causes the surface temperature of the control unit to exceed 55 °C, provide an appropriate shielding plate.
- If there is a possibility that the fluid and drive part freeze, please take measures to prevent freezing. ②POSITIONING

Should be positioned through 90° upward from horizontal. Provide space around the product to allow manual operation, inspection and replacement work.

Maintenance space for upper part of actuator				
PAX	More than 90 mm			

③OTHER NOTES

Until the wiring is completed there must be no condensation or flooding in the interior of the actuator, after piping. Protective caps on the cable gland are not waterproof.

WIRING

- · Do not wiring outdoors on a rainy day.
- Check the power supply and voltage.
 Connect the signal as shown in the wiring diagram.
 Do not connect unnecessarily terminal.
- Use suitable flexible cable (Φ5 to 10.5 mm). Lock and seal the cable completely to prevent condensation inside the actuator.
- Built-in terminal block can clamp up to 1.5 mm in diameter without using solderless terminal.
- Allow proper cable slack for maintenance.
- Actuator should be electrically grounded. Use the terminal marked (≟) inside the actuator.

PREVENT DEW CONDENSATION

- When installing the cover after wiring, perform the bolt by the temporary tightening procedure and the permanent tightening procedure to tightly and securely tighten the rubber packing so that water does not enter from the outside.
- Tighten the cable gland nut so that there is no leakage from the wire entrance.

CONTROL

- Use shielded wire for signal wiring where high level noise is generated or when the wiring distance is long.
- Control with a 1 to 5 V input signal becomes an input resistance 250 Ω . Provide a voltage that can safely 20 mA or more than.
- Check whether the MODE change DIP SW on a circuit board substrate is set up correctly. When wiring, if wiring of a signal is mistaken, it will not operate correctly. Contact us when you use two valve or more by one controller or indicator.
- Input signal circuit is non-isolated.
- Do not connect DC (-) wire to other DC (-) common.
- The input signal and operation mode are set as follows. (Factory shipped)

Input signal	4 to 20 mA / 1 to 5 V	
Operation mode	Mode A	
Operation	SHUT by decreased signal OPEN by increased signal	

OPERATION

①TESTING

- Make sure that power supply voltage is correct. Also check operating position, wiring, speed and signals.
- During trial operation, check that valve movement and output signal are correct.
- **©CONFIRM THE OPERATING CONDITION**
- Adjust fluid condition, controller setting, sensor etc. so that stable control is achieved.
- When used in an unstable control state, the life of the actuator and the valve will be shortened.
- The desired control state is stable at the target value. Adjust the PID setting value of the controller when overshooting the target value greatly, when not converging for a long time or hunting operation. Also, when the time delay is large, please consider the sensor position.
- **3ATTENTION**
- Be sure to set the DIP-SW before turning on the power supply.
- Keep power supplied for built-in space heater to prevent condensation inside actuator.
- Do not touch the moving parts of actuator in operation.
- Never put anything on the actuator or make it into a foothold.

MANUAL OPERATION

OPRECAUTIONS

- Manual operation should be a temporary operation.
- · Be sure to turn off the power before manual
- operation.
- **②NOTE**

For manual operation, do not give more than the rated torque and make at a slow rate. Actuator might be damaged if excessive force is added.



MAINTENANCE

- To prevent electric shock, be sure to turn off the power when removing the actuator cover.
- Do the routine maintenance at least once in half a year.
 - Inspection items
 - · Confirm operation of opening and closing.
 - · Confirm that an actuator is not hot excessively. · Confirm existence of abnormal noise and
 - vibration during operation.
 - Confirm whether screws are loose or not.
 - Confirm that water or condensation no remains in the actuator.

TROUBLE S		I	
Problem	Cause	Solution	
Actuator does not move.	Faulty wiring.	Correct the wiring.	
	Voltage and input signal are not coming.	Check the voltage and input signal.	
	Incorrect voltage.	When it's burned out by excess voltage, replace the actuator.	
	Connection or wiring is not correct.	Correct the miswiring and misconnection. Be careful not to mistake the plus and minus of wiring.	
	Short the circuit, contact failure.	Review wires and connection.	
	Motor is too old.	Replace the actuator.	
Operation is unstable.	Excess surge or voltage was applied.	Replace the actuator.	
	Rainwater entered the actuator.		
	Added high harmonics noise from an inverter.	Attachment a filter for each inverter maker option.	
	Effect of high level noise.	Use the shielded wire and ground the wiring. Separate signal wire from power line.	
Stop in the mid position. (Input signal's 1 to 5 V.)	Signal voltage source capacity shortage.	Use a voltage source that can be made to flow more than 20 mA. Please contact us.	
Stop in the mid position.	Overload protector runs because of over-torque.	Motor protection circuit returns by the signal of operation of an opposite direction. Turn on the power again.	

For more information contact NIPPON VALVE CONTROLS, INC. for consultation.