

# Instruction manual Electric Actuated Butterfly Valve Z

SP-1519

# Please read this manual before installation and use.

#### **GENERAL**

Light weight, low price and economical butterfly valve.

This type designed for 3-piece structure and it is easy to maintenance.

Actuator

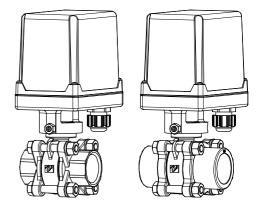
AM: For AC power.

AH1: For AC power. (High speed)

DM: For DC power.

PAX : Proportional control.

ACR : Emergency Shut Off.



Threaded End Rc

Socket End

# Valve

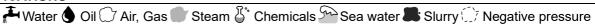
Z type It is small, light weight and economical butterfly valve.

This type designed for 3 piece structure

and it is easy to maintenance.

# **PRODUCT CODE**

Threaded End Rc **Z** -5 Τ Z type U Z -Socket End (PVC) 7 Т (C-PVC) Ζ 7 Τ Н (9)(1)(2) (3) (4) (5) (6) (7) (8) (10)(11)(1) Actuator (4) Sizing code (6) Body material (10) Option 0: Standard T: SCS13A AM1 AM2 AH1 AK: Aluminum alloy DM0 DM2 PAX ACR 1: Light motor cover 2 : Heavy (7) Cap material M1: Manual lever (2) Valve U: SCS14A C1: Flexible cable Z-(5) Connection 5: Threaded End Rc (7) Socket material (11) Operation mode (PAX) (3) Voltage 7 : Socket End P:PVC Nil: Mode A 1:100/110 V AC H: C-PVC J: Mode B 2:200/220 V AC 2: 100 to 220 V AC (ACR) (8) Seat material 0:24V DC E: EPDM B: NBR V:FKM (9) Size [mm] ex.  $25 A \rightarrow 025$ 



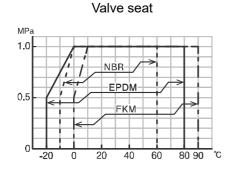
Valve type		Z			
Design		3 piece structure			
Connection		Threaded End Rc	Socket End		
Fluid		<b>#4080</b>	#608°50;		
Max pressure		1 MPa			
Size [mm]		015 to 050			
Material	Body	SCS13A			
	Disc	PPS			
	Сар	SCS14A	-		
	Socket	-	PVC C-PVC		
	Seat	EPDM NBR FKM			
Stem seal	O-ring	Depend on seat material			

# **SEAT MATERIAL GUIDE**

Seat material	Fluid temp.	Use
EPDM	-20 to +80 °C	in Smill
NBR	-10 to +60 °C	<b>6</b> 00
FKM	-0 to +90 °C	B* ()/

- Note) EPDM seat cannot be used for oil.
  - Unsuitable for steam or hot water over 80 °C.
  - Can flow the seawater with PVC socket and EPDM sheet.

# PRESSURE & TEMPERATURE RATING

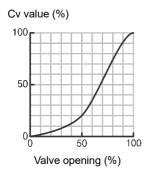


1.0

Cap / Socket

# 0.5

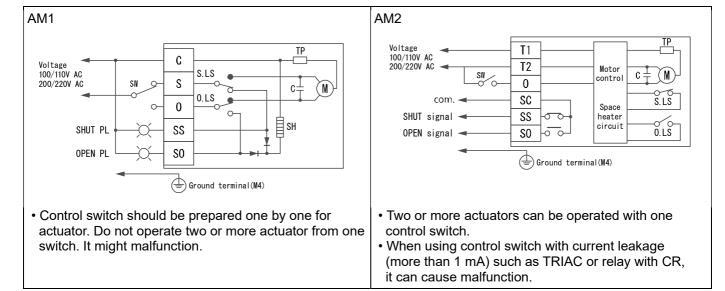
# INHERENT FLOW CHARACTERISTIC



Range ability 30:1

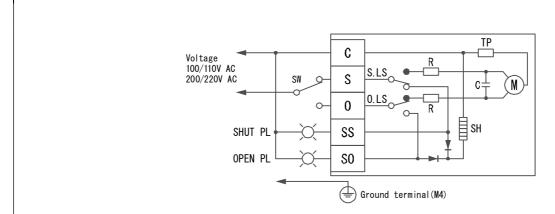
# AM1 AM2 type

Actuator type (□:Voltage code)	AM1-030-□	AM1-070-□	AM1-180-□	AM2-030-□	AM2-070-□	AM2-180-□	
Voltage		100 / 110 V AC ±10 % 50/60 Hz (Voltage code: 1) 200 / 220 V AC ±10 % 50/60 Hz (Voltage code: 2)					
Rated torque [N·m]	3	7	18	3	7	18	
Operation time [s]	5.4 / 4.5 (50/60 Hz)	15.5 / 13 (50/60 Hz)	16 / 13.5 (50/60 Hz)	5.4 / 4.5 (50/60 Hz)	15.5 / 13 (50/60 Hz)	16 / 13.5 (50/60 Hz)	
Power consumption [VA]	16		19	18		19	
Motor	Synchronous	motor					
Overload protection	Thermal prote	ector					
Method of operation	Transfer inpu	t type		a-contactinput type, with built-in relay			
Operation		Power to S $\rightarrow$ SHUT (SHUT PL is lit.) Power to O $\rightarrow$ OPEN (OPEN PL is lit.)			SW is OFF $\rightarrow$ SHUT (SHUT signal is output.) SW is ON $\rightarrow$ OPEN (OPEN signal is output.)		
Input signal current	Nil	Nil			9 mA (O-terminal) Leakage current in SW: less than 1 mA		
Output signal rating	Resistance load 3 A 250 V AC (Minimum 0.1 A)			Resistance loa Micro load	d 0.5 A 125 \ 2 A 30 V D 1 mA 5 V I	C	
Duty cycle	20 % 15 min.						
Ambient temperature	-20 to 55 °C						
Space heater 1 W							
Manual operation	Direct operation of actuator by loosening lock screw						
Enclosure	Equivalent to	Equivalent to IP65 (IEC 60529)					
Housing material Aluminum alloy die cast + Polycarbonate resin cover							
Terminal block For bare wire 0.14 to 1.5 mm² (AWG 26 to 14) Ground terminal: M4							
Conduct port	G3/8 Cable g	land (for Φ5 to	o 10.5 mm cab	ole)			



# AH1 type

Actuator type (□:Voltage code)		AH1-030-□ AH1-070-□		AH1-180-□	
Voltage			(- )		
Rated torque	[N·m]	3	7	18	
Operation time	[s]	3 / 2.5 (50/60 Hz)		6 / 5 (50/60 Hz)	
Power consumption	[VA]	19	50		
Motor		Synchronous motor	Reversible motor		
Overload protection		Thermal protector			
Method of operation		Transfer input type	Transfer input type		
Operation		Power to S $\rightarrow$ SHUT (SHUT PL is lit.) Power to O $\rightarrow$ OPEN (OPEN PL is lit.)			
Output signal rating	utput signal rating Resistance load 3 A 250 V AC (Minimum 0.1 A)				
Duty cycle		20 % 15 min.			
Ambient temperature		-20 to 55 °C			
Space heater		0.5 W	1 W		
Manual operation		Direct operation of output shaft			
Enclosure		Equivalent to IP65 (IEC 60529)			
Housing material		Aluminum alloy die cast + Polycarbonate resin cover			
Terminal block For bare wire 0.14 to 1.5 mm² (AWG 26 to 14) Ground terminal: M			d terminal: M4		
Conduct port G3/8 Cable gland (for Φ5 to 10.5 mm cable)					

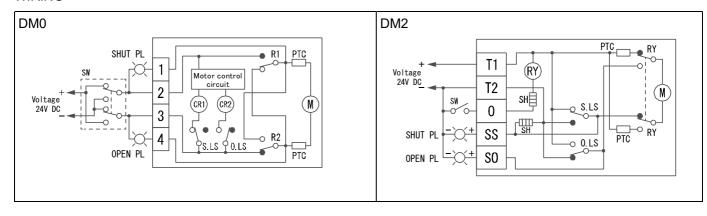


Note) Control switch should be prepared one by one for actuator.

Do not operate two or more actuator from one switch. It might malfunction.

# DM0 DM2 type

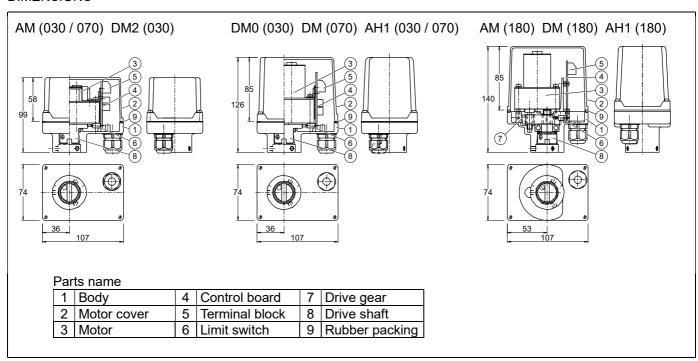
Actuator type	DM0-030-0	DM0-070-0	DM0-180-0	DM2-030-0	DM2-070-0	DM2-180-0	
Voltage	24 V DC	24 V DC					
Rated torque [N·n	1] 3	7	18	3	7	18	
Operation time	s] 0.8 to 1.5	2 to 3	4 to 6	2 to 3.5	2 to 3	4 to 6	
Power consumption (Max) [V	A] 24			10	24		
Motor	DC motor						
Overload protection	Thermistor						
Method of operation	Switching po	plarity type		a-contactinpo	ut type, with bu	ıilt-in relay	
Operation	$2 + 3 - \rightarrow SHUT$ (SHUT PL $3 + 2 - \rightarrow OPEN$ (OPEN PL						
Input signal current	Nil			16.2 mA (O-terminal)			
Output signal rating	Resistance l Micro load	Resistance load 2 A 30 A DC Micro load 1 mA 5 V DC			Resistance load : Less than 1 A 24 V DC		
Duty cycle	20 % 15 mir	1.					
Ambient temperature	-20 to 55 °C						
Space heater	heater 1 W						
Manual operation Direct operation of output sha			shaft				
Enclosure	Equivalent to	Equivalent to IP65 (IEC 60529)					
Housing material	Aluminum alloy die cast + Polycarbonate resin cover						
Terminal block	For bare wire 0.14 to 1.5 mm² (AWG 26 to 16)						
Conduct port	G3/8 Cable	G3/8 Cable gland (for Φ5 to 10.5 mm cable)					



# **OPTIONAL PARTS**

Specifications	Code No.	AM	AH1	DM	Remarks
Aluminum alloy motor cover	AK	0	0	0	
Manual lever	M1		0	0	Detachable lever
Flexible cable (Approx. 300 mm long)	C1	0	0	0	

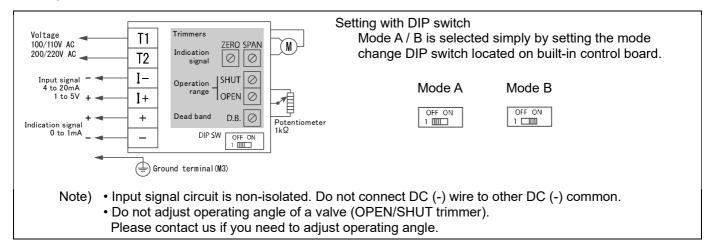
# **DIMENSIONS**



# PAX type

Actuator type (□:Voltage	code)	PAX-050-□	PAX-120-□	
Voltage		100 / 110 V AC ±10 % 50/60 Hz (Code 200 / 220 V AC ±10 % 50/60 Hz (Code	,	
Rated torque	[N·m]	5	12	
Operation time	[s]	14 / 12 (50/60 Hz)	30 / 25 (50/60 Hz)	
Power consumption	[VA]	9.5		
Motor		Synchronous motor (Triac control)		
Overload protection		Impedance protect		
Method of operation		Proportional control		
Input signal		4 to 20 mA / 1 to 5 V (Input resistance: 250 Ω)		
Operation *1		[Mode A] SHUT by decreased signal ↔ OPEN by increased signal (Standard) [Mode B] SHUT by increased signal ↔ OPEN by decreased signal (Option: J)		
Indication signal		0 mA : SHUT $\leftrightarrow$ 1 mA : OPEN (External load resistance: less than 3 k $\Omega$ ) Common in mode A / B		
Resolution		Less than 0.2 %		
Duty cycle		100 %		
Ambient temperature		-20 to 55 °C		
Space heater		1 W		
Manual operation		Direct operation of actuator by loosening lo	ock screw	
Enclosure		Equivalent to IP65 (IEC 60529)		
Housing material		Aluminum alloy die cast + Polycarbonate r	esin cover	
Terminal block		For bare wire 0.2 to 1.5 mm² (AWG 26 to 16) Ground terminal: M3		
Conduct port		G3/8 Cable gland (for Φ5 to 10.5 mm cable	e)	

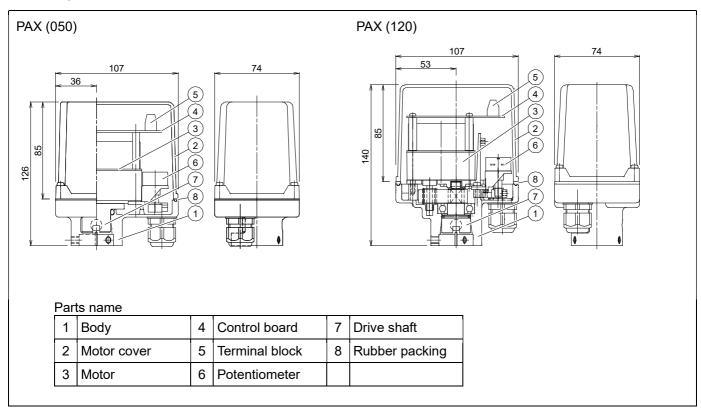
<sup>\*</sup>¹ Change by DIP switch. (Standard → Mode B)



# **OPTIONAL PARTS**

Specification	s	Code No.	PAX	Remarks
Aluminum al	loy motor cover	AK	0	
Flexible cabl	e (Approx. 300 mm long)	C1	0	
Operation	SHUT by decreased signal ↔ OPEN by Increased signal	Nil	0	Mode A
	SHUT by increased signal ↔ OPEN by decreased signal	J	0	Mode B

# **DIMENSION**



# ADJUSTMENT (PAX)

① Dead band

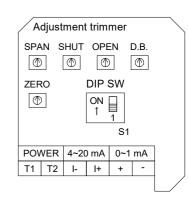
Turn the trimmer clockwise for wide the dead band as necessary. It is useful to prevent the hunting reaction of actuator.

\*Each trimmer on a built-in control board.

② Operating range

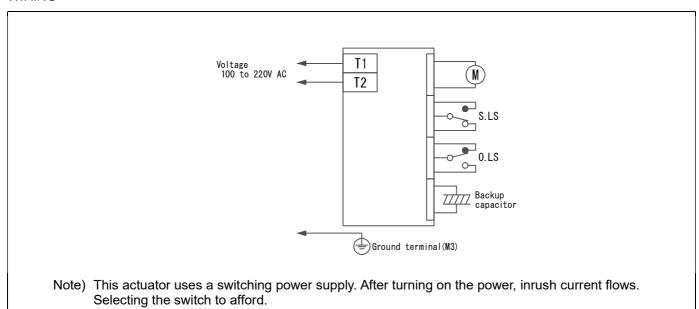
Do not adjust operating angle of a valve (OPEN, SHUT trimmer). Please contact us if you need to adjust operating angle.

③ Operating speed (Speed control) No adjustment required. (ZERO, SPAN trimmer)



# ACR type

Actuator type		ACR-030-2
Voltage		100 to 220 V AC ±10 % 50/60 Hz
Rated torque	[N·m]	3
Operation time	[s]	When power supply on → less than 12 When power supply shut off → less than 6
Power consumption (Max)	[VA]	30
Motor		DC motor
Overload protection		Thermistor
Method of operation		Operation by power ON / OFF
Operation		Power OFF : SHUT ↔ Power ON : OPEN (Standard) Power ON : SHUT ↔ Power OFF : OPEN (Option: 45)
Built-in power supply		Electric double layer capacitor
Duty cycle		20 % 15 min.
Ambient temperature		-20 to 50 °C
Manual operation		Direct operation of output shaft
Enclosure		Equivalent to IP65 (IEC 60529)
Housing material		Aluminum alloy die cast + Polycarbonate resin cover
Terminal block		For bare wire 0.14 to 1.5 mm² (AWG 26 to 16) Ground terminal: M3
Conduct port		G3/8 Cable gland (for Φ5 to 10.5 mm cable)



# **HANDLING & STORAGE**

#### **①HANDLING**

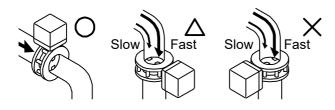
Do not drop or throw the product as it may break. ②STORAGE

- Store away from dust, moisture and direct sunlight. If possible, store in the original package.
- Do not remove a dust proof cap until the piping. ③CHECKING
- Check the product code, power supply, and voltage before installation.
- Make sure that the bolts are not loose.
- The DIP switch should be set up before the power is turned on. Do not touch unnecessary switches. (PAX)

#### **INSTALLATION**

#### **OPRECAUTIONS**

- Flush the pipeline carefully before installing the valve. Foreign particles, such as sand or pieces of welding electrode, will damage the disk and seats.
- When piping the valve disk should be closed before mounting.
- · Avoid oil or grease when using EPDM seat.
- The butterfly valve should be piped upstream of the elbow. When piping downstream from the elbow, considered a straight line that is at least five times the length of the pipe.



• The valve stem should be mounted perpendicular to the flow for biased fluid.

#### **②PIPING**

- Using a pipe with too long a thread will damage the
- If sealing tape or sealant gets inside the valve, the valve seat leaks or malfunctions.
- When connecting a pipe or fitting to a valve, use a tool on the octagonal or hexagonal part of the insertion side and screw it.
- Refer to the recommended tightening torque table and do not apply excessive torque.

Valve size [mm]	Torque [N·m]
015	25 to 35
020	40 to 50
025	50 to 60
032	60 to 80
040	75 to 85
050	90 to 110

#### 3Socket End

Should use adhesive suitable for valve materials.

#### **@ENVIRONMENT**

- Do not install in place where corrosive gas is present or where vibration is heavy (0.5 G or more).
- When radiant heat causes the surface temperature of the control unit to exceed 55 °C (more than 50 °C for ACR only), provide an appropriate shielding plate.
- If there is a possibility that the fluid and drive part freeze, please take measures to prevent freezing.

#### **SPOSITIONING**

Should be positioned through 90° upward from horizontal. Provide space around the product to allow manual operation, inspection and replacement work.

Marg	Margin required around the actuator for maintenance				
AM (	030 / 0	70) I	More than 65 mm		
AM	AH1	DM	PAX	ACR	More than 90 mm

#### **©OTHER NOTES**

Until the wiring is completed there must be no condensation or flooding in the interior of the actuator, after piping. Protective caps on the cable gland are not waterproof.

#### WIRING

- Do not wiring outdoors on a rainy day.
- Check the power supply and voltage.

  Connect the signal as shown in the wiring diagram.
- · Do not connect unnecessarily terminal.
- Use suitable flexible cable (Φ5 to 10.5 mm).
   Lock and seal the cable completely to prevent condensation inside the actuator.
- Built-in terminal block can clamp up to 1.5 mm² in diameter without using solderless terminal.
- Allow proper cable slack for maintenance.

# PREVENT DEW CONDENSATION

- When installing the cover after wiring, perform the bolt by the temporary tightening procedure and the permanent tightening procedure to tightly and securely tighten the rubber packing so that water does not enter from the outside.
- Tighten the cable gland nut so that there is no leakage from the wire entrance.

# **CONTROL**

#### ①AM1, AH1

Control switch should be prepared one by one for actuator. Do not operate two or more actuator from one switch. It might malfunction.

#### ②AM2

- Two or more actuators can be operated with one control switch.
- When using control switch with current leakage (more than 1 mA) such as TRIAC or relay with CR, it can cause malfunction.
- When wiring is long distance or handling a weak current signal, it may be affected by induced voltage or noise. In this case, please use countermeasures such as using a shielded wire, separating it from other power cables.

# ③DC POWER SUPPLY (DM0, DM2)

- It is usable with a battery and full-wave rectification circuit.
- Consider an inrush current of motor.
   (It is 1.5 to 3 times of consumed current.)
- They may cause malfunction with decreasing voltage by the long wiring.
- Do not use power supply that require more than 1 second with rise and fall time.
- Inrush current flows when the switching power supply is turned on. Use a fuse, relay or switch with sufficient capacity.
- It may be affected by induced voltage or noise. Please use countermeasures such as using a shielded wire, separating it from other power cables.
   (When a power supply is off, the terminal block should make the induced voltage less than 10V.)

#### **©PAX**

- Use shielded wire for signal wiring where high level noise is generated or when the wiring distance is long.
- Control with a 1 to 5 V input signal becomes an input resistance 250  $\Omega$ . Provide a voltage that can safely 20 mA or more than.
- Check whether the MODE change DIP SW on a circuit board substrate is set up correctly.
   When wiring, if wiring of a signal is mistaken, it will not operate correctly. Contact us when you use two valve or more by one controller or indicator.
- Input signal circuit is non-isolated.
   Do not connect DC (-) wire to other DC (-) common.
- The input signal and operation mode are set as follows. (Factory shipped)

Input signal	4 to 20 mA / 1 to 5 V
Operation mode	Mode A
Operation	SHUT by decreased signal OPEN by increased signal

#### **OPERATION**

#### **①TESTING**

- Make sure that power supply voltage is correct. Also check operating position, wiring, speed and signals.
- During trial operation, check that valve movement and output signal are correct.
- ②DUTY CYCLE (AM, AH1, DM, ACR)

Confirm that the operation frequency is within the specified duty cycle.

Use beyond the load time rate range will affect product life. Also, it may cause burnout.

Duty cycle is a value that regulates the opening / closing frequency of the actuator. The meaning of 20 % 15 minutes for Duty cycle is that 3 minutes (20 % of 15 minutes) operation is possible. The calculated value obtained by dividing 3 minutes by the operation time is the number of times of operation within 15 minutes.

#### **3 CONFIRM THE OPERATING CONDITION (PAX)**

- Adjust fluid condition, controller setting, sensor etc. so that stable control is achieved.
- When used in an unstable control state, the life of the actuator and the valve will be shortened.
- The desired control state is stable at the target value. Adjust the PID setting value of the controller when overshooting the target value greatly, when not converging for a long time or hunting operation. Also, when the time delay is large, please consider the sensor position.

### **4ATTENTION**

- Be sure to set the DIP-SW before turning on the power supply. (PAX)
- Keep power supplied for built-in space heater to prevent condensation inside actuator.
   (AM, AH1, DM, PAX)
- Do not touch the moving parts of actuator in operation.
- Do not insert a reverse signal during operation.
   It may shorten the life of product. (AM, AH1, DM, PAX)
- Never put anything on the actuator or make it into a foothold.

# **MANUAL OPERATION**

**OPRECAUTIONS** 

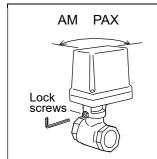
- Manual operation should be a temporary operation.
- Be sure to turn off the power before manual operation.

If it is not left after power supply cut off for 6 hours, it will operate with capacitor charge voltage. Make sure that the following procedure in case of emergency.

- 1) Put an allen wrench into the hold on drive shaft and turn slowly.
- 2) Internal limit switch gets used from a switch setting cam, then the motor of actuator will operate and it hold in the position.
- 3) The capacitor discharge in about 1 minute, perform manual operation.

#### **3NOTE**

For manual operation, do not give more than the rated torque and make at a slow rate. Actuator might be damaged if excessive force is added.



Actuator can be easily removed from the valve by loosing 3 lock screws, and that allows direct operation of the valve. After operation, be sure to put back the actuator to the original position and lock.



Put an allen wrench (5 mm) or a lever (Φ5.7) into the hole on drive shaft and turn slowly. Manual lever is optional.

# **MAINTENANCE**

- To prevent electric shock, be sure to turn off the power when removing the actuator cover.
- Do the routine maintenance at least once in half a year.

Inspection items

- · Confirm operation of opening and closing.
- · Confirm that an actuator is not hot excessively.
- Confirm existence of abnormal noise and vibration during operation.
- · Confirm whether screws are loose or not.
- Confirm that water or condensation no remains in the actuator.
- Turn off the power and check if the valve operates normally with built-in capacitor. (ACR)
- Confirm the fluid temperature or pressure.
- · Confirm the leak from valve stem.

#### TROUBLE SHOOTING

TROUBLE SHOOTING			
Problem	Cause	Solution	
Actuator does not move.	Faulty wiring.	Correct the wiring.	
	No voltage is coming.	Check the voltage.	
	Incorrect voltage.	When it's burned out by excess voltage, replace the actuator.	
	Connection or wiring is not correct. PAX	Correct the miswiring and misconnection. Be careful not to mistake the plus and minus of wiring.	
	Short the circuit, contact failure.	Review wires and connection.	
	Motor is too old.	Replace the actuator.	
Operation is unstable.	Excess surge or voltage was applied.	Replace the actuator.	
	Rainwater entered the actuator.		
	Switch leakage current is large. AM2	Current leakage should be less than 1 mA.	
Operation is unstable. PAX	Added high harmonics noise from an inverter.	Attachment a filter for each inverter maker option.	
	Effect of high level noise.	Use the shielded wire and ground the wiring. Separate signal wire from power line.	
Stop in the mid position. (Input signal's 1 to 5 V.) PAX	Signal voltage source capacity shortage.	Use a voltage source that can be made to flow more than 20 mA. Please contact us.	
Stop in the mid position.	Continuous irregular stop will shorten the motor life and wear the gear. Turn off the power and check.  AM1 AM2 AH1-030		

Problem	Cause	Solution
Stop in the mid position.	Biting of valve seat.	Remove a foreign object.
	Overload protector runs because of over-torque.	Turn off the power for about 3 minutes to remove a heat from motor protection circuit. AM1 AM2 AH1 DM2 DM0 ACR
		Motor protection circuit returns by the signal of operation of an opposite direction. Turn on the power again. PAX
	Capacitor is too old.	Replace the actuator.
Leakage from valve seat	Seat is worn or damaged.	Replace the valve.
Leakage from valve stem	Packing is worn or distorted.	

For more information contact NIPPON VALVE CONTROLS, INC. for consultation.