

Instruction manual Electric Actuated Ball Valve BR BS GS VR

SP-1531

Please read this manual before installation and use.

GENERAL

Flange-end ball valve and compact electric actuator.

Actuator

AM: For AC power.

AH1: For AC power. (High speed)

DM: For DC power.

PAX: Proportional control.

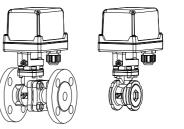
Valve

BR type For various fluids and general use.

BS type For Wafer

VR type For control

GS type For Wafer. (JIS 10K / 20K)





PRODUCT CODE

BR type BS type		B R
VR type		P A X V R _
	(Standard port)	P A X V R 🔲 📗 1 U U 🗌 R 0 1 5 - 📋 - 📗
GS type	(V-port)	P A X G S 🗌 🗎 3 U U 🔲 V 📑 📑 - 📋 - 📗
	(Full port)	☐ G S ☐ G S ☐ 3 U U ☐ - ☐ ☐ - ☐ ☐
	(Standard port)	GS 0 3 U U R 0 4 0 - :
		(1) (2) (3) (4) (5) (6) (7) (8) (9) (10) (11)

- (1) Actuator AM1 AM2 AH1 DM0 DM2 PAX
- (4) Sizing code 0 : Standard 1: Light

2 : Heavy

(7) Ball material

(8) Seat material

T:SCS13A U: SUS316 / SCS14A

(10) Option

AK: Aluminum alloy motor cover M1: Manual lever

C1: Flexible cable

(2) Valve

(3) Voltage

BR BS **VR** GS

(5) Connection 1: JIS 10K

(6) Body material

T: SCS13A

U: SCS14A

3: JIS 20K

F:F-PTFE G: R-PTFE R:R-F-PTFE

K: PEEK I:API C: R-PEEK

M: SUS316 + Stellite

0:24V DC

1:100/110 V AC

2:200/220 V AC

(9) Size [mm] ex. $25 A \rightarrow 025$ (11) Operation mode (PAX)

Nil: Mode A J: Mode B



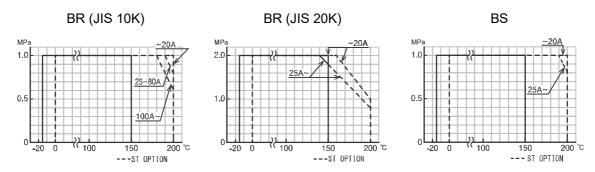
BR BS Type

Valve type		BR			BS		
Design		2-way, Full p	2-way, Full port			ll port)	
Connection		JIS10K Flang	ged-end	JIS20K Flanged-end	JIS Flanges 10K		
Fluid		# 6 00	B. C.7		#4008 0		
Max pressur	e	1 MPa		2 MPa	1 MPa		
Size [mm]		015 to 032		015 to 025	015 to 032		
Material	Body	SCS14A	SCS13A	SCS13A	SCS13A	SCS14A	
	Ball	SCS14A	SCS13A	SCS13A	SCS13A	SCS14A	
Seat F-PTFE R-PTFE R-F-		PTFE	F-PTFE R-PTF	E R-F-PTFE			
Stem seal	Stem seal Packing R-PTFE			R-PTFE			
	O-ring	FKM			FKM		

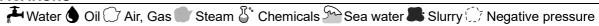
The optional for steam fluids.

Valve type		Option code	O-ring			
BR	BS	ST	Replace (Steam resistant FKM)			

PRESSURE & TEMPERATURE RATING



Note) Insulation options are required for use with fluids more than 150 $^{\circ}$ C.



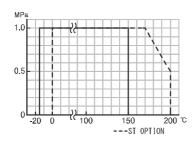
VR Type

Valve type		VR			
Design		2-way, V-pc	ort		
Connection		JIS10K Flai	nged-end		
Fluid		* ••••••••••••••••••••••••••••••••••••			
Max pressur	е	1 MPa			
Size [mm]		R015	015 to 025		
Material	Body	SCS14A			
	Ball	SUS316	SCS14A		
Seat		R-PTFE R-F-PTFE			
Stem seal Packing		R-PTFE			
	O-ring	FKM			

The optional for steam fluids.

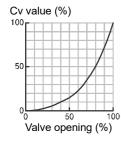
Valve type	Option code	O-ring
VR	ST	Replace (Steam resistant FKM)

PRESSURE & TEMPERATURE RATING



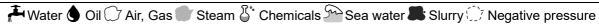
Note) Insulation options are required for use with fluids more than 150 °C.

INHERENT FLOW CHARACTERISTIC



Range ability

VR-1UUG R 015 100:1 VR-1UUG - 015 to 025 50:1

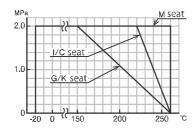


GS type

Valve type		GS					
Design		2-way, Wafer					
		V-port		Full	port	Standard port	
Connection JIS Flanges 10K / 20K							
Fluid		₹46 ○ 6 °					
Max pressu	re	2 MPa					
Size [mm]		V015 to V032		015	to 080	R040 to R150	
Material	Body	SCS14A		•		·	
Ball		SCS14A (H	SCS14A (HCr plated)				
	Seat	R-PTFE	PEEK	API	R-PEEK	SUS316 + Stellite	
Stem seal	Packing	R-PTFE					

Note) API cannot be used with steam fluid.

PRESSURE & TEMPERATURE RATING

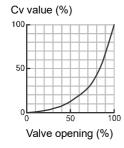


- Note) Option for use in fluid temperature more than 170 °C.
 - We prefer to K seat depends on pressure or environmental conditions. Please consult us for your specifications.

SEAT LEAKAGE VOLUME (JIS B 2005-4)

	Seat material	Leakage rate	Remarks
G	R-PTFE	None	
K	PEEK		
ı	API		
С	R-PEEK	10 ⁻⁴ × rated Cv value × 10 ⁻³ or less.	Class IV × 10 ⁻³ or less.
	R-PEEK (V-port)	10 ⁻⁴ × rated Cv value × 10 ⁻³ × 8 or less.	Class IV × 10 ⁻³ × 8 or less.
М	SUS316 + Stellite	10 ⁻⁴ × rated Cv value or less.	Class IV or less.
	SUS316 + Stellite (V-port)	10 ⁻⁴ × rated Cv value × 8 or less.	Class IV × 8 or less.

INHERENT FLOW CHARACTERISTIC



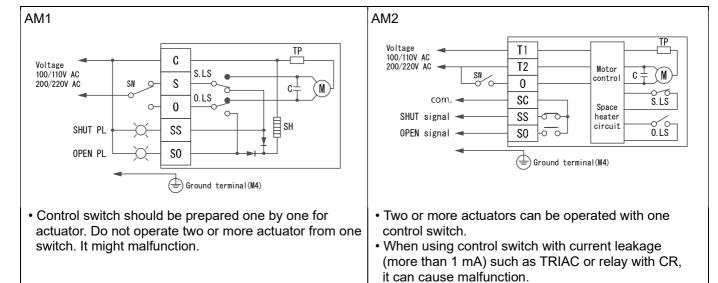
Range ability

GS-3UU□ V 015 to 032 50:1 (V-port)
GS-3UU□ - 015 to 080 200:1 (Full port)
GS-3UU□ R 040 to 150 100:1 (Standard port)

AM1 AM2 type

Actuator type (□:Voltage code)	AM1-030-□			AM2-030-□	AM2-070-□	AM2-180-□
Voltage	100 / 110 V A 200 / 220 V A			age code: 1) age code: 2)		
Rated torque [N·m]	3	3 7 18			7	18
Operation time [s]	5.4 / 4.5 (50/60 Hz)	15.5 / 13 (50/60 Hz)	16 / 13.5 (50/60 Hz)	5.4 / 4.5 (50/60 Hz)	15.5 / 13 (50/60 Hz)	16 / 13.5 (50/60 Hz)
Power consumption [VA]	16		19	18		19
Motor	Synchronous	motor				
Overload protection	Thermal prote	ector				
Method of operation Transfer input type				a-contactinput type, with built-in relay		
Operation	Power to S \rightarrow SHUT (SHUT PL is lit.) Power to O \rightarrow OPEN (OPEN PL is lit.)			SW is OFF → SHUT (SHUT signal is output.) SW is ON → OPEN (OPEN signal is output.)		
Input signal current	Nil			9 mA(O-terminal) Leakage current in SW: less than 1 mA		
Output signal rating	Resistance lo	oad 3 A 250 V (Minimum		Resistance load 0.5 A 125 V AC 2 A 30 V DC Micro load 1 mA 5 V DC		
Duty cycle	20 % 15 min.					
Ambient temperature	-20 to 55 °C					
Space heater	1 W					
Manual operation	Direct operati	on of actuator	by loosening	J lock screw		
Enclosure Equivalent to IP65 (IEC 60529)						
Housing material Aluminum alloy die cast + Polycarbonate resin cover						
Terminal block	For bare wire	0.14 to 1.5 m	m² (AWG 26 t	o 14) Ground	terminal: M4	
Conduct port	G3/8 Cable g	land (for Φ5 to	o 10.5 mm cab	ole)		

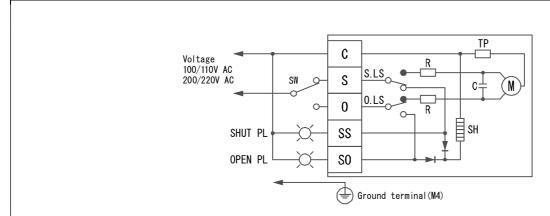
WIRING



AH1 type

Actuator type (□:Voltage code)		AH1-030-□	AH1-070-□	AH1-180-□
Voltage		100 / 110 V AC ±10 % 50/6 200 / 220 V AC ±10 % 50/6	,	
Rated torque	[N·m]	3	7	18
Operation time	[s]	3 / 2.5 (50/60 Hz)		6 / 5 (50/60 Hz)
Power consumption	[VA]	19	50	
Motor		Synchronous motor	Reversible motor	
Overload protection		Thermal protector		
Method of operation		Transfer input type		
Operation		Power to S \rightarrow SHUT (SHUT PL is lit.) Power to O \rightarrow OPEN (OPEN PL is lit.)		
Output signal rating		Resistance load 3 A 250 V A	C (Minimum 0.1 A)	
Duty cycle		20 % 15 min.		
Ambient temperature		-20 to 55 °C		
Space heater		0.5 W	1 W	
Manual operation		Direct operation of output sha	ft	===
Enclosure		Equivalent to IP65 (IEC 60529)		
Housing material		Aluminum alloy die cast + Polycarbonate resin cover		
Terminal block	For bare wire 0.14 to 1.5 mm² (AWG 26 to 14) Ground terminal: I			d terminal: M4
Conduct port G3/8 Cable gland (for Φ5 to 10.5 mm cable)				

WIRING



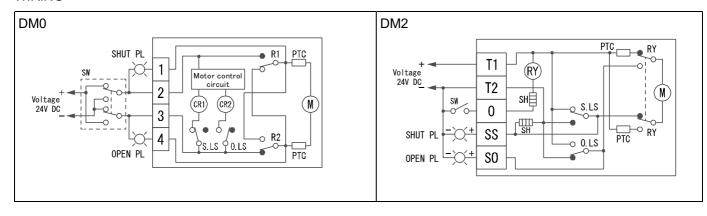
Note) Control switch should be prepared one by one for actuator.

Do not operate two or more actuator from one switch. It might malfunction.

DM0 DM2 type

Actuator type	DM0-030-0	DM0-070-0	DM0-180-0	DM2-030-0	DM2-070-0	DM2-180-0	
Voltage	24 V DC						
Rated torque [N·n	1] 3	7	18	3	7	18	
Operation time	s] 0.8 to 1.5	2 to 3	4 to 6	2 to 3.5	2 to 3	4 to 6	
Power consumption (Max) [V	A] 24			10	24		
Motor	DC motor						
Overload protection	Thermistor						
Method of operation	Switching po	plarity type		a-contactinpo	ut type, with bu	ıilt-in relay	
Operation					SW is OFF \rightarrow SHUT (SHUT PL is lit.) SW is ON \rightarrow OPEN (OPEN PL is lit.)		
Input signal current	Nil			16.2 mA (O-terminal)			
Output signal rating	Resistance l Micro load	oad 2 A 30 1 mA 5		Resistance lo	oad : Less thar	1 1 A 24 V DC	
Duty cycle	20 % 15 mir	1.					
Ambient temperature	-20 to 55 °C						
Space heater	1 W						
Manual operation	Direct opera	tion of output	shaft				
Enclosure	Equivalent to	Equivalent to IP65 (IEC 60529)					
Housing material	Aluminum a	lloy die cast +	Polycarbona	te resin cover			
Terminal block	For bare wir	e 0.14 to 1.5	mm² (AWG 26	6 to 16)			
Conduct port	G3/8 Cable	G3/8 Cable gland (for Φ5 to 10.5 mm cable)					

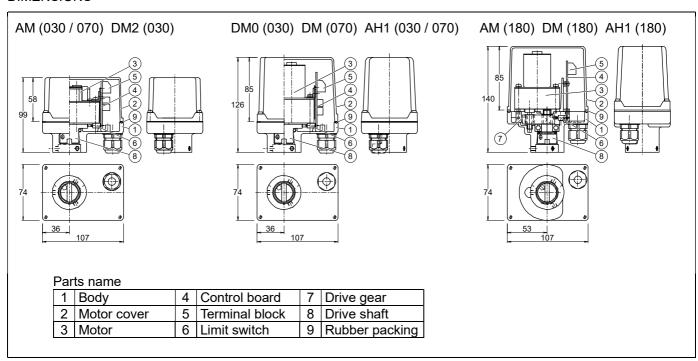
WIRING



OPTIONAL PARTS

Specifications	Code No.	AM	AH1	DM	Remarks
Aluminum alloy motor cover	AK	0	0	0	
Manual lever	M1		0	0	Detachable lever
Flexible cable (Approx. 300 mm long)	C1	0	0	0	

DIMENSIONS

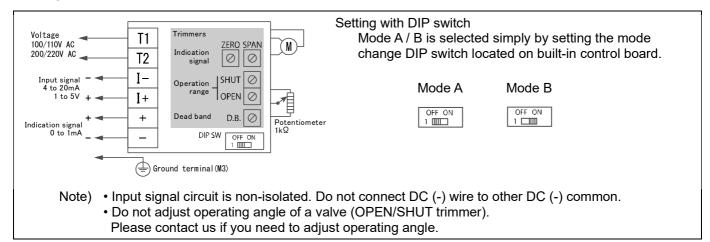


PAX type

Actuator type (□:Voltage code)		PAX-050-□	PAX-120-□	
Voltage	<u> </u>	100 / 110 V AC ±10 % 50/60 Hz (Code: 1) 200 / 220 V AC ±10 % 50/60 Hz (Code: 2)		
Rated torque	[N·m]	5	12	
Operation time	[s]	14 / 12 (50/60 Hz)	30 / 25 (50/60 Hz)	
Power consumption	[VA]	9.5		
Motor		Synchronous motor (Triac control)		
Overload protection		Impedance protect		
Method of operation		Proportional control		
Input signal		4 to 20 mA / 1 to 5 V (Input resistance:	250 Ω)	
Operation *1	Operation *1 [Mode A] SHUT by decreased signal ↔ OPEN by increased signal (Standard Mode B] SHUT by increased signal ↔ OPEN by decreased signal (Option			
Indication signal		0 mA : SHUT ↔ 1 mA : OPEN (External lo Common in mode A / B	ad resistance: less than 3 kΩ)	
Resolution		Less than 0.2 %		
Duty cycle		100 %		
Ambient temperature		-20 to 55 °C		
Space heater		1 W		
Manual operation		Direct operation of actuator by loosening lo	ock screw	
Enclosure		Equivalent to IP65 (IEC 60529)		
Housing material		Aluminum alloy die cast + Polycarbonate r	esin cover	
Terminal block		For bare wire 0.2 to 1.5 mm² (AWG 26 to 16) Ground terminal: M3		
Conduct port		G3/8 Cable gland (for Φ5 to 10.5 mm cable	e)	

^{*}¹ Change by DIP switch. (Standard → Mode B)

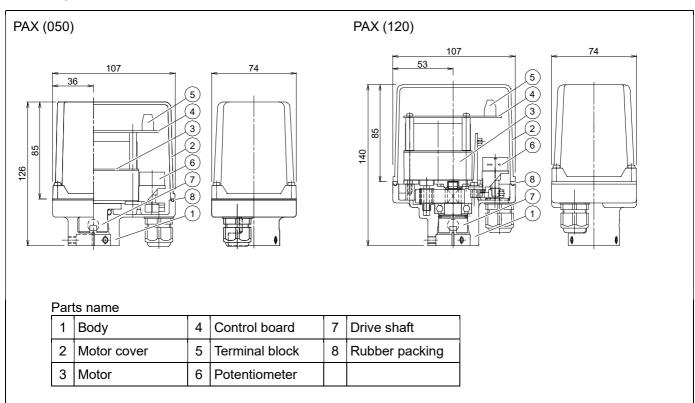
WIRING



OPTIONAL PARTS

Specifications			PAX	Remarks
Aluminum alloy motor cover			0	
Flexible cable (Approx. 300 mm long)			0	
Operation	SHUT by decreased signal ↔ OPEN by Increased signal	Nil	0	Mode A
	SHUT by increased signal ↔ OPEN by decreased signal	J	0	Mode B

DIMENSION



ADJUSTMENT (PAX)

① Dead band

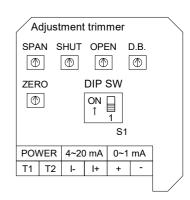
Turn the trimmer clockwise for wide the dead band as necessary. It is useful to prevent the hunting reaction of actuator.

*Each trimmer on a built-in control board.

② Operating range

Do not adjust operating angle of a valve (OPEN, SHUT trimmer). Please contact us if you need to adjust operating angle.

③ Operating speed (Speed control) No adjustment required. (ZERO, SPAN trimmer)



HANDLING & STORAGE

①HANDLING

Do not drop or throw the product as it may break.

- **2STORAGE**
- · Store away from dust, moisture and direct sunlight. If possible, store in the original package.
- Do not remove a dust proof cap until the piping.
- **3CHECKING**
- · Check the product code, power supply, and voltage before installation.
- Make sure that the bolts are not loose.
- The DIP switch should be set up before the power is turned on. Do not touch unnecessary switches. (PAX)

INSTALLATION

OPRECAUTIONS

- Flush the pipeline carefully before installing the valve. Foreign particles, such as sand or pieces of welding electrode, will damage the ball and seats.
- For valves with specified flow direction (GS, VR) or with ST / SC option, check the arrows on the product before piping.

②PIPING FLANGES

- · Gasket should be selected appropriately to suit the fluid, pressure and temperature. Use spring washer to prevent from decreasing surface pressure gasket when the temperature change happens frequently.
- Tighten all bolts using crossover method to load the joint evenly.
- · Wafer type ball valve is put between two seats of flanged-end and tightened with long bolts. (BS, GS)

3ENVIRONMENT

- Do not install in place where corrosive gas is present or where vibration is heavy (0.5 G or more).
- When radiant heat causes the surface temperature of the control unit to exceed 55 °C, provide an appropriate shielding plate.
- If there is a possibility that the fluid and drive part freeze, please take measures to prevent freezing. **@POSITIONING**

Should be positioned through 90° upward from

horizontal. Provide space around the product to allow manual operation, inspection and replacement work.

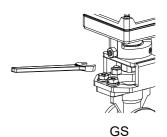
Margin required around the actuator for maintenance				
AM (030 / 070) DM2 (030)			More than 65 mm	
AM	AH1	DM	PAX	More than 90 mm

SOTHER NOTES

Until the wiring is completed there must be no condensation or flooding in the interior of the actuator, after piping. Protective caps on the cable gland are not waterproof.

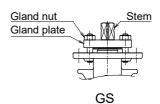
©CAUTIONS FOR MAINTENANCE (GS)

Do not keep warm for maintenance of the valve gland.



TIGHTEN THE GLAND NUTS (GS)

- · Check that there is no leakage from the gland packing.
- If it leakage, tighten gland nuts by alternately. Do not over-tighten the gland nuts.



Val	Valve size [mm]		Recommended torques [N·m]
V015 V020	015 020	-	2
V025 V032	025 032	R040	3.5

WIRING

- Do not wiring outdoors on a rainy day.
- · Check the power supply and voltage. Connect the signal as shown in the wiring diagram.
- Do not connect unnecessarily terminal.
- Use suitable flexible cable (Φ5 to 10.5 mm). Lock and seal the cable completely to prevent condensation inside the actuator.
- Built-in terminal block can clamp up to 1.5 mm in diameter without using solderless terminal.
- Allow proper cable slack for maintenance.
- · Actuator should be electrically grounded. Use the terminal marked (\(\pm\)) inside the actuator.

PREVENT DEW CONDENSATION

- When installing the cover after wiring, perform the bolt by the temporary tightening procedure and the permanent tightening procedure to tightly and securely tighten the rubber packing so that water does not enter from the outside.
- Tighten the cable gland nut so that there is no leakage from the wire entrance.

CONTROL

①AM1, AH1

Control switch should be prepared one by one for actuator. Do not operate two or more actuator from one switch. It might malfunction.

②AM2

- Two or more actuators can be operated with one control switch.
- When using control switch with current leakage (more than 1 mA) such as TRIAC or relay with CR, it can cause malfunction.
- When wiring is long distance or handling a weak current signal, it may be affected by induced voltage or noise. In this case, please use countermeasures such as using a shielded wire, separating it from other power cables.

③DC POWER SUPPLY (DM0, DM2)

- It is usable with a battery and full-wave rectification circuit.
- Consider an inrush current of motor.
 (It is 1.5 to 3 times of consumed current.)
- They may cause malfunction with decreasing voltage by the long wiring.
- Do not use power supply that require more than 1 second with rise and fall time.
- Use shielded wire for signal wiring where high level noise is generated or when the wiring distance is long.
- Control with a 1 to 5 V input signal becomes an input resistance 250 Ω . Provide a voltage that can safely 20 mA or more than.
- Check whether the MODE change DIP SW on a circuit board substrate is set up correctly.
 When wiring, if wiring of a signal is mistaken, it will not operate correctly. Contact us when you use two valve or more by one controller or indicator.
- Input signal circuit is non-isolated.
 Do not connect DC (-) wire to other DC (-) common.
- The input signal and operation mode are set as follows. (Factory shipped)

Input signal	4 to 20 mA / 1 to 5 V
Operation mode	Mode A
Operation	SHUT by decreased signal OPEN by increased signal

OPERATION

①TESTING

- Make sure that power supply voltage is correct. Also check operating position, wiring, speed and signals.
- During trial operation, check that valve movement and output signal are correct.

②DUTY CYCLE (AM, AH1, DM)

Confirm that the operation frequency is within the specified duty cycle.

Use beyond the load time rate range will affect product life. Also, it may cause burnout.

Duty cycle is a value that regulates the opening / closing frequency of the actuator. The meaning of 20 % 15 minutes for Duty cycle is that 3 minutes (20 % of 15 minutes) operation is possible. The calculated value obtained by dividing 3 minutes by the operation time is the number of times of operation within 15 minutes.

3CONFIRM THE OPERATING CONDITION (PAX)

- Adjust fluid condition, controller setting, sensor etc. so that stable control is achieved.
- When used in an unstable control state, the life of the actuator and the valve will be shortened.
- The desired control state is stable at the target value. Adjust the PID setting value of the controller when overshooting the target value greatly, when not converging for a long time or hunting operation. Also, when the time delay is large, please consider the sensor position.

ATTENTION

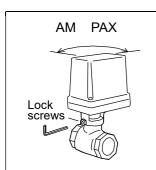
- Be sure to set the DIP-SW before turning on the power supply. (PAX)
- Keep power supplied for built-in space heater to prevent condensation inside actuator.
- Do not touch the moving parts of actuator in operation.
- Do not insert a reverse signal during operation. It may shorten the life of product. (AM, AH1, DM)
- Never put anything on the actuator or make it into a foothold.

MANUAL OPERATION

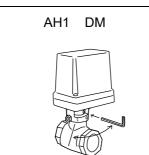
①PRECAUTIONS

- Manual operation should be a temporary operation.
- Be sure to turn off the power before manual operation. ②NOTE

For manual operation, do not give more than the rated torque and make at a slow rate. Actuator might be damaged if excessive force is added.



Actuator can be easily removed from the valve by loosing 3 lock screws, and that allows direct operation of the valve. After operation, be sure to put back the actuator to the original position and lock.



Put an allen wrench (5 mm) or a lever (Φ5.7) into the hole on drive shaft and turn slowly. Manual lever is optional.

MAINTENANCE

- To prevent electric shock, be sure to turn off the power when removing the actuator cover.
- Do the routine maintenance at least once in half a year.

Inspection items

- · Confirm operation of opening and closing.
- · Confirm that an actuator is not hot excessively.
- Confirm existence of abnormal noise and vibration during operation.
- · Confirm whether screws are loose or not.
- Confirm that water or condensation no remains in the actuator.
- Confirm the fluid temperature or pressure.
- Confirm the leak from valve stem.
- Confirm the bolt tightening torque.

TROUBLE SHOOTING

TROUBLE SHOOTING					
Problem	Cause	Solution			
Actuator does not move.	Faulty wiring.	Correct the wiring.			
	No voltage is coming.	Check the voltage.			
	Incorrect voltage.	When it's burned out by excess voltage, replace the actuator.			
	Connection or wiring is not correct. PAX	Correct the miswiring and misconnection. Be careful not to mistake the plus and minus of wiring.			
	Short the circuit, contact failure.	Review wires and connection.			
	Motor is too old.	Replace the actuator.			
Operation is unstable.	Excess surge or voltage was applied.	Replace the actuator.			
	Rainwater entered the actuator.				
	Switch leakage current is large. AM2	Current leakage should be less than 1 mA.			
Operation is unstable. PAX	Added high harmonics noise from an inverter.	Attachment a filter for each inverter maker option.			
	Effect of high level noise.	Use the shielded wire and ground the wiring. Separate signal wire from power line.			
Stop in the mid position. (Input signal's 1 to 5 V.) PAX	Signal voltage source capacity shortage.	Use a voltage source that can be made to flow more than 20 mA. Please contact us.			
Stop in the mid position.	Continuous irregular stop will shorten the motor life and wear the gear. Turn off the power and check. AM1 AM2 AH1-030				

Problem	Cause	Solution
Stop in the mid position.	Biting of valve seat. The scale has adhered to the valve ball.	Remove a foreign object.
	Overload protector runs because of over-torque.	Turn off the power for about 3 minutes to remove a heat from motor protection circuit. AM1 AM2 AH1 DM2 DM0
		Motor protection circuit returns by the signal of operation of an opposite direction. Turn on the power again. PAX
Leakage from valve body	Valve cap get loose. Valve body is damaged.	Replace the valve.
Leakage from valve seat	Seat is worn or damaged.	Replace the valve.
		Replace the valve seat.
Leakage from valve stem	Stem packing is worn or distorted.	Replace the valve.
		Replace the packing.
Leakage from valve gland GS	Gland packing is worn or distorted.	Tighten the gland nut.
		Replace the gland packing.

For more information contact NIPPON VALVE CONTROLS, INC. for consultation.